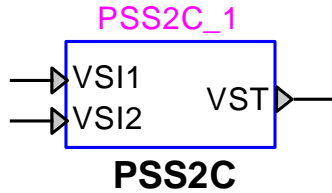


# Exciters and Governors: Power System Stabilizer PSS2C



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## 1 Description

This device is an implementation of the IEEE type PSS2C power system stabilizer model. This device is implemented as described in [1]. Implementation details can be viewed by inspecting the subcircuit of this device. The exponents M and N of the “ramp-tracking” filter are 2 and 4, respectively.

### 1.1 Pins

This device has 3 pins:

Pin name	Type	Description	Units
VSI1	Input	Speed	pu
VSI2	Input	Electrical power	pu
VST	Output	PSS output (equivalent of terminal voltage)	pu

### 1.2 Parameters

The default set of parameters can be found in [1].

#### 1.2.1 Data tab

The parameters on the Data tab are:

1. **Gain  $K_{S1}$** : power system stabilizer gain
2. **Gain  $K_{S2}$** : power system stabilizer gain
3. **Gain  $K_{S3}$** : power system stabilizer gain
4. **Time constant  $T_6$** : transducer time constant
5. **Time constant  $T_7$** : transducer time constant
6. **Time constant  $T_{W1}$** : washout time constant
7. **Time constant  $T_{W2}$** : washout time constant
8. **Time constant  $T_{W3}$** : washout time constant

9. **Time constant  $T_{W4}$** : washout time constant
10. **Filter time constant  $T_8$** : transducer time constant
11. **Filter time constant  $T_9$** : washout time constant
12. **Lead time constant  $T_1$** : numerator (lead) compensating time constant (first block)
13. **Lag time constant  $T_2$** : denominator (lag) compensating time constant (first block)
14. **Lead time constant  $T_3$** : numerator (lead) compensating time constant (second block)
15. **Lag time constant  $T_4$** : denominator (lag) compensating time constant (second block)
16. **Lead time constant  $T_{10}$** : numerator (lead) compensating time constant (third block)
17. **Lag time constant  $T_{11}$** : denominator (lag) compensating time constant (third block)
18. **Lead time constant  $T_{12}$** : numerator (lead) compensating time constant (fourth block)
19. **Lag time constant  $T_{13}$** : denominator (lag) compensating time constant (fourth block)
20. **Maximum output  $V_{STMAX}$** : Maximum PSS output
21. **Minimum output  $V_{STMIN}$** : Minimum PSS output
22. **Maximum input  $V_{SI1MAX}$** : Input signal #1 maximum limit
23. **Minimum input  $V_{SI1MIN}$** : Input signal #1 minimum limit
24. **Maximum input  $V_{SI2MAX}$** : Input signal #2 maximum limit
25. **Minimum input  $V_{SI2MIN}$** : Input signal #2 minimum limit
26. **PSS activation  $P_{PSSON}$** : Generator MW threshold for PSS activation
27. **PSS de-activation  $V_{PSSOFF}$** : Generator MW threshold for PSS de-activation

## 2 Initial conditions

The initial output signal is zero from the steady-state solution.

## 3 References

- [1] "IEEE Recommended Practice for Excitation System Models for Power System Models for Power System Stability Studies," IEEE Standard 421.5-2016.