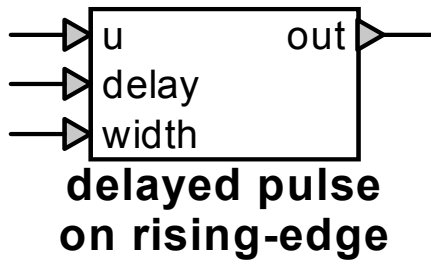


# Control function: delayed pulse on rising-edge



Control function: delayed pulse on rising-edge.....	1
1 Description .....	1
1.1 Pins.....	1
1.2 Parameters .....	1
1.3 Input.....	2
1.4 Output.....	2
1.5 Representation .....	2

## 1 Description

This device produces a pulse of amplitude 1, with starting and stopping determined dynamically by the value of the inputs.

### 1.1 Pins

This device has four pins:

<i>pin</i>	<i>type</i>	<i>description</i>
u	input	triggering signal
delay	input	delay before starting
width	input	variable pulse width
out	output	generated pulses

### 1.2 Parameters

The following parameters must be defined:

<i>parameter</i>	<i>description</i>	<i>units</i>
stepped	=1 to indicate stepped transitions =0 to indicate ramped transitions	

The value of the parameter *stepped* determines whether the device operates with *stepped* or *ramped* transitions. In *stepped* mode (the default for ideal logical signals), the output is represented as a stepped signal, where changes in value are observed as vertical steps at the time they occur. In *ramped* mode, the value transitions of the output are seen as ramps between  $t-\Delta t$  and  $t$ .

### 1.3 Input

The input pins may be connected to any control signal.

### 1.4 Output

The output is a series of pulses generated dynamically according to the variable values of triggering, delay and width provided as inputs.

The representation of the output as having *stepped* or *ramped* transitions is determined by the value given to the parameter *stepped*.

### 1.5 Representation

The implementation of the model can be inspected by opening the device's subcircuit.

The value of the output is 0 or 1 as determined by the following rules:

$$\begin{aligned} \text{out} &= 1 && \text{when } T_{\text{on}} \leq t_{\text{trig}} < T_{\text{off}} \\ \text{out} &= 0 && \text{otherwise} \end{aligned} \quad (1)$$

where

$$\begin{aligned} T_{\text{on}} &= t_{\text{trig}} + \text{delay} \\ T_{\text{off}} &= T_{\text{on}} + \text{width} \end{aligned} \quad (2)$$

and where

$$t_{\text{trig}} \text{ is held constant for at least } \text{delay} + \text{width} \text{ seconds} \quad (3)$$