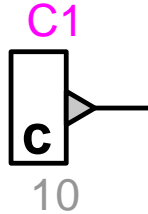


# Control device : constant



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## 1 Description

This device provides a constant value C as the output signal.  
The constant value is a user-defined parameter.

### 1.1 Pins

This device has one signal pin:

<i>pin</i>	<i>description</i>	<i>value when unconnected</i>
out	output	as calculated

### 1.2 Parameters

Selection options for the output signal value:

<i>option</i>	<i>value</i>	<i>rules</i>
zero	output = zero	
constant value	output = user-defined value	any value

### 1.3 History

No user-defined history is required.

## 1.4 Scopes

Setting the scope flag enables monitoring of the output signal during the simulation.

## 1.5 Output signal interpolation

No output signal interpolation is required.

## 2 Time-domain representation

In the time domain at  $t > 0$ ,  
the output value is calculated as follows:

$$\text{out}(t) = C \quad (1)$$

## 3 Steady-state representation

In the time domain at  $t > 0$ ,  
the output value is calculated as follows:

$$\text{out}(0) = C \quad (2)$$

## 4 Netlist

### 4.1 Format

Netlist format:

```
_c_cst;name;1;1;out,  
value,scope,
```

<i>field</i>	<i>description</i>	<i>value</i>
<code>c_cst</code>	part name	
<code>name</code>	instance name	
<code>1</code>	pin count	
<code>1</code>	pin count	
<code>out</code>	signal name of the output	
<code>value</code>	output value	constant value
<code>scope</code>	monitoring, optional	"?s" for enabled

The comma separated data is saved into the ParamsA attribute of this device.