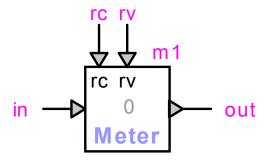
Control signal meter

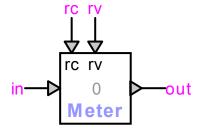


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1 Description

This device measures the rms value or the frequency of a control signal connected as input.

1.1 Pins



This device has four signal pins:

pin	description	value when unconnected
in	input	0
out	output	as calculated
rc	reset control	0
rv	reset value	0

1.2 Parameters

Selection options for the type of meter:

meter type	output value
no meter	0
rms meter	rms value of input signal at given frequency
frequency meter	frequency of input signal in given frequency range

Base frequency of the rms meter:

parameter	description	units
frequency	base frequency of the measured signal	Hz

Frequency range of the frequency meter:

parameter	description	units
minimum frequency	minimum frequency of the measured signal	Hz
maximum frequency	maximum frequency of the measured signal	Hz

1.3 History

Selection options for the history value of the output signal:

option	value	rules
not defined	history(t) = undefined	
zero	history(t) = zero	
constant value	history(t) = user-defined value	any value
function value	history(t) = user-defined function	constant or f(t)

1.4 Scopes

Setting the scope flag enables monitoring of the output signal during the simulation.

1.5 Output signal interpolation

During the simulation, the output value of this device is calculated at successive instants t at intervals Δt . Between these simulation instants, the output value can be set to vary in one of two modes, ramped or stepped:

mo	de	output value between t-∆t and t¯	value at t ⁻	<i>value at</i> t
ran	nped	interpolated linearly	calculated at t	calculated at t
		between values out($t - \Delta t$) and out(t^-)		
ste	pped	remains at out($t - \Delta t$)	remains at out(t - Δ t)	calculated at t

2 Time-domain representation

In the time-domain calculation at t>0, the output value is calculated as follows:

> rms meter:

when
$$rc(t) > 0$$

 $out(t) = rv(t)$ (1)

else

$$out(t) = \sqrt{\frac{1}{period} \cdot \int_{t-period}^{t} in(t)^2 \cdot dt}$$
 (2)

frequency meter:

when
$$rc(t) > 0$$

out(t) = $rv(t)$ (3)

else

$$out(t) = \frac{0.5}{\text{interval between successive zero crossings of in(t)}}$$
 (4)

intervals outside given frequency range are ignored the input signal is assumed to have no dc offset

3 Steady-state representation

In the steady-state calculation at t=0, the output value is calculated as follows:

if history is defined,
$$out(0) = history(0)$$

else $out(0) = 0$ (5)

4 Netlist

4.1 Netlist format for no meter

Netlist format:

_c_cst;name;4;4;out,in,rc,rv, 0,step/ramp,scope,

field	description	value
c_cst	part name	
name	instance name	
4	pin count	
4	pin count	
out	signal name of the output	
in	signal name of the input	
rc	signal name of the reset control	
rv	signal name of the reset value	
0	output value	
step/ramp	output interpolation	"S1" for stepped
		"S0" for ramped
scope	monitoring, optional	"?s" for enabled

The comma separated data is saved into the ParamsA attribute of this device.

4.2 Netlist format for rms meter

Netlist format:

_c_rms;name;4;4;out,in,rc,rv, history,frequency,step/ramp,scope, history function expression

field	description	value
c_rms	part name	
name	instance name	
4	pin count	
4	pin count	
out	signal name of the output	
in	signal name of the input	
rc	signal name of the reset control	
rv	signal name of the reset value	
history	history	constant value
		or "H" for function
frequency	base frequency of measured signal	constant value
step/ramp	calculation mode	"S1" for stepped
		"S0" for ramped
scope	monitoring, optional	"?s" for enabled
history function expression	optional, required when history field is "H"	

The comma separated data is saved into the ParamsA attribute of this device. The history function expression is saved into the ModelData attribute.

4.3 Netlist format for frequency meter

Netlist format:

_c_freq;name;4;4;out,in,rc,rv, history,fmin,fmax,step/ramp,scope, history function expression

field	description	value
c_freq	part name	
name	instance name	
4	pin count	
4	pin count	
out	signal name of the output	
in	signal name of the input	
rc	signal name of the reset control	
rv	signal name of the reset value	
history	history	constant value or "H" for function
fmin	minimum frequency	constant value
fmax	maximum frequency	constant value
step/ramp	calculation mode	"S1" for stepped
		"S0" for ramped
scope	monitoring, optional	"?s" for enabled
history function expression	optional, required when history field is "H"	

The comma separated data is saved into the ParamsA attribute of this device. The history function expression is saved into the ModelData attribute.