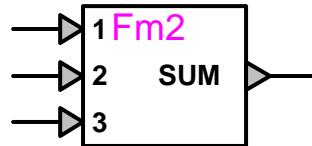


# Control device : f(u)

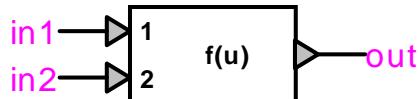


1 Description .....	1
1.1 Pins.....	1
1.2 Pre-defined functions.....	1
1.3 User-defined functions.....	2
1.4 History .....	3
1.5 Scopes.....	3
1.6 Output signal interpolation.....	3
2 Time-domain representation .....	3
3 Steady-state representation .....	3
4 Netlist .....	3
4.1 Format .....	3
4.2 Examples.....	4

## 1 Description

This device applies the specified function to its inputs. The number of inputs is arbitrary, and can be zero. The function may be defined arbitrarily by the user, or selected from a list of pre-defined functions. User-defined functions may refer to simulation variables such as the value of time or time-step, and to the value of the applied input signals.

### 1.1 Pins



This device has one or more signal pins:

pin	description	value when unconnected
in1	input 1	0
...	more inputs	0
out	output	as calculated

### 1.2 Pre-defined functions

When selecting a pre-defined function, the function is considered to be applied to all inputs of the function. Some of the pre-defined functions require a specific number of inputs, while others work with a list of any number of inputs. When selecting a pre-defined function, the drawing of the function is automatically modified according to the selection. The following pre-defined functions are available:

➤ logical functions

*function    description    output value*

NOT	not	out = NOT(in > 0)
AND	and	out = (in1 > 0) AND (in2 > 0) AND ...
OR	or	out = (in1 > 0) OR (in2 > 0) OR ...
XOR	exclusive or	out = (in1 > 0) XOR (in2 > 0) XOR ...
NAND	not and	out = (in1 > 0) NAND (in2 > 0) NAND ...
NOR	not or	out = (in1 > 0) NOR (in2 > 0) NOR ...

➤ numerical functions

*function    description    output value*

RECIP	multiplicative inverse	when in(t) = 0 then out = infinity else out = 1/in
ABS	absolute value	out =  in
SQRT	square root	out = $\sqrt{in}$
EXP	exponential	out = $e^{in}$
LOG	base-e logarithm	out = $\log_e(in)$
LOG10	base-10 logarithm	out = $\log_{10}(in)$
DEG	radians to degrees	out = in · 180 / $\pi$
RAD	degrees to radians	out = in · $\pi$ / 180
SUM	sum	out = in1 + in2 + ...
PROD	product	out = in1 · in2 · ...
MIN	minimum	out = min(in1, in2, ...)
MAX	maximum	out = max(in1, in2, ...)
NORM	Euclidian norm	out = $\sqrt{(in1^2 + in2^2 + ...)}$

➤ trigonometric functions

*function    output value*

SIN	out = sin(in)
COS	out = cos(in)
TAN	out = tan(in)
COTAN	out = cotan(in)
ASIN	out = $\sin^{-1}(in)$
ACOS	out = $\cos^{-1}(in)$
ATAN	out = $\tan^{-1}(in)$
SINH	out = sinh(in)
COSH	out = cosh(in)
TANH	out = tanh(in)

### 1.3 User-defined functions

User-defined functions are arbitrary expressions written according to the expression syntax rules.

## 1.4 History

Selection options for the history value of the output signal:

option	value	rules
zero	Inherit from inputs	
constant value	history(t) = user-defined value	any value, 0 means inherit, use 0.0 to get 0
function value	history(t) = user-defined function	constant or f(t)

## 1.5 Scopes

Setting the scope flag enables monitoring of the output signal during the simulation.

## 1.6 Output signal interpolation

During the simulation, the output value of this device is calculated at successive instants  $t$  at intervals  $\Delta t$ . Between these simulation instants, the output value can be set to vary in one of two modes, ramped or stepped:

mode	output value between $t - \Delta t$ and $t^-$	value at $t^-$	value at $t$
ramped	interpolated linearly between values out( $t - \Delta t$ ) and out( $t^-$ )	calculated at $t^-$	calculated at $t$
stepped	remains at out( $t - \Delta t$ )	remains at out( $t - \Delta t$ )	calculated at $t$

## 2 Time-domain representation

In the time-domain calculation at  $t > 0$ , the output value is calculated as follows:

$$\text{out}(t) = f(t, \text{in}1(t), \text{in}2(t), \dots) \quad (1)$$

## 3 Steady-state representation

In the steady-state calculation at  $t = 0$ , the output value is calculated as follows:

$$\begin{aligned} \text{if history is defined, } \text{out}(0) &= \text{history}(0) \\ \text{else } \text{out}(0) &= f(t, \text{in}1(0), \text{in}2(0), \dots) \end{aligned} \quad (2)$$

## 4 Netlist

### 4.1 Format

Netlist format:

```
_c_fu;name;npins;npins;out,list(inputs),
history,step/ramp,scope,
history function expression
;
output function expression
```

<i>field</i>	<i>description</i>	<i>value</i>
c_fu name npins npins	part name instance name pin count pin count	1+count(inputs) 1+count(inputs)
out list(inputs)	signal name of the output signal names of the inputs	
history	history	constant value or "H" for function
step/ramp	calculation mode	"S1" for stepped "S0" for ramped
scope	monitoring, optional	"?s" for enabled
history function expression	optional, required when history field is "H"	
;	optional, required when the above line is present	
output function expression	provides selected output function	

## 4.2 Examples

Netlist example with 2 inputs, math function choice, history expression, step mode, scope:

```
_c_fu;f1;3;3;s1,s2,s3,  
H,S1,?s,  
5*COS(10*pi/180)  
;  
u[1]*t-3*ABS(u[2])
```

Netlist example with 3 inputs, selected math function “PROD”, zero initial value, ramp mode, no scope:

```
_c_fu;f2;4;4;s4,s5,s6,s7,  
0,S0,  
[PROD]
```