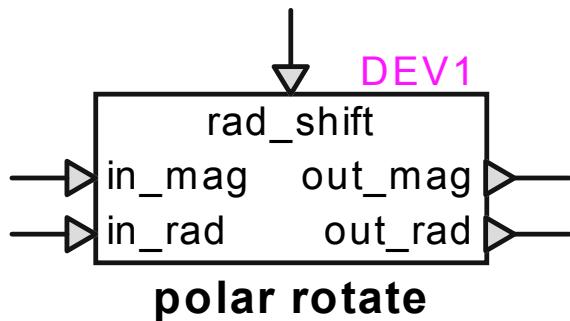


# Phasor operation : polar rotate



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## 1 Description

This device rotates a vector or phasor represented by its polar coordinates.

### 1.1 Pins

This device has five pins:

<i>pin</i>	<i>type</i>	<i>description</i>	<i>units</i>
in_mag	input pin	input magnitude	any
in_rad	input pin	input angle	rad
rad_shift	input pin	rotation angle	rad
out_mag	output pin	output magnitude	same as in_mag
out_rad	output pin	output angle	rad

### 1.2 Parameters

No parameters are required for this device.

### 1.3 Input

The input pins may be connected to any control signals.

### 1.4 Output

The outputs are the polar coordinates of the input vector rotated by a variable angle.

The operation is immediate, and is calculated as follows:

out\_mag = in\_mag  
out\_rad = in\_rad +  $\theta$   
where  $\theta$  is the rotation angle (1)