# **Exciters and Governors: Exciter IEEET2**



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Hossein Ashourian, Henry Gras, Jean Mahseredjian, 1/6/2021 2:09 AM

# **Description**

This device is an implementation of the IEEE Type 2 Excitation System. This device is implemented as described in [1]. Implementation details can be viewed by inspecting the subcircuit of this device.

# 1.1 Pins

This device has 6 pins:

Pin name	Туре	Description	Units
VREF	Input	Reference voltage of the stator terminal voltage	pu
Efss	Input	Steady-state field voltage at t = 0, for initialization	pu
VC	Input	Terminal voltage of synchronous machine,	pu
	-	transducer output	-
VS	Input	Power System Stabilizer signal	pu
EFD	Output	The Field voltage signal	pu
VF	Output	The excitation system stabilizer signal	pu

## 1.2 Parameters

The default set of parameters can be found in [1].

#### 1.2.1 Data tab

The parameters on the Data tab are:

- 1. Gain K<sub>A</sub>: voltage regulator gain
- Time constant T<sub>A</sub>: voltage regulator time constant
   Voltage V<sub>Rmax</sub>: maximum voltage regulator output
- 4. Voltage V<sub>Rmin</sub>: minimum voltage regulator output
- 5. Gain K<sub>F</sub>: rate feedback gain

- 6. Time constant T<sub>F1</sub>: rate feedback time constant
- 7. Time constant T<sub>F2</sub>: rate feedback time constsnt

# 1.2.2 Exciter tab

The parameters on the Exciter tab are:

- 1. Gain K<sub>E</sub>: exciter field proportional constant
- 2. Time constant T<sub>E</sub>: exciter field time constant
- 3. Field voltage E<sub>FD1</sub>: exciter voltage point which is near the exciter ceiling voltage
- 4. Field voltage E<sub>FD2</sub>: exciter voltage point which is near 75% of E<sub>FD1</sub>
- 5. Saturation function output SE\_E<sub>FD1</sub>: exciter saturation function value at E<sub>FD1</sub>
- 6. Saturation function output SE\_E<sub>FD2</sub>: exciter saturation function value at E<sub>FD2</sub>

The exciter saturation function is defined as

$$S_{F} = A_{FX} e^{B_{EX} E_{FD}}$$
 (1)

which gives the approximation saturation for any  $E_{FD}$  (exciter output voltage). According to [2] (see pages 562 and 563), the coefficients  $A_{EX}$  and  $B_{EX}$  can be found from:

$$A_{EX} = \frac{S_{V_{E2}}^4}{S_{V_{E1}}^3}$$
 (2)

$$B_{EX} = \frac{4}{V_{E1}} \ln \left( \frac{S_{V_{E1}}}{S_{V_{E2}}} \right)$$
 (3)

In the literature [2]  $V_{E1} = V_{E_{max}}$  and  $V_{E2} = V_{E_{0.75 max}}$ 

## 2 Initial conditions

The reference voltage VREF can be manually or automatically set by connecting or not connecting the input signal VREF, respectively. When VREF is not connected (the signal is zero), the reference voltage is internally found from the steady-state solution. When VREF is connected, its initial value must match the per unit steady-state voltage of the stator terminal voltage, since otherwise the generator voltage will not start at the actual steady-state.

## 3 References

- [1] PSS®E MODEL LIBRARY PSS®E 32.0.5, Siemens Energy, Inc.
- [2] P. M. Anderson and A. A. Fouad, "Power system control and stability", second edition, IEEE Press, Wiley Interscience, 2003.