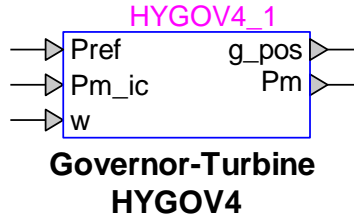


# Exciters and Governors: Governor-Turbine HYGOV4



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## 1 Description

This device is an implementation of a general model for turbine and governor HYGOV4. This device is implemented as described in [1]. Implementation details can be viewed by inspecting the subcircuit of this device.

### 1.1 Pins

This device has 5 pins:

Pin name	Type	Description	Units
Pref	Input	Power reference from load controller LCBF1	pu
Pm_ic	Input	Steady-state mechanical power at t = 0, for initialization	pu
w	Input	Mechanical speed	pu
g_pos	Output	Gate position	pu
Pm	Output	Turbine mechanical power	pu

### 1.2 Parameters

The default set of parameters are obtained from [1].

#### 1.2.1 Governor tab

The parameters on the Governor tab are:

1. **Deadband width  $db_1$** : deadband width of speed governor
2. **Deadband hysteresis  $E_{RR}$** : deadband hysteresis of speed governor
3. **Time constant  $T_G$** : gate servo time constant
4. **Time constant  $T_P$** : pilot servo valve time constant
5. **Time constant  $T_R$** : dashpot time constant

6. **Permanent droop SIGMA**: permanent droop
7. **Temporary droop DELTA**: temporary droop
8. **Maximum opening velocity  $U_0$** : maximum opening velocity
9. **Maximum closing velocity  $U_C$** : maximum closing velocity
10. **Maximum valve opening  $P_{MAX}$** : maximum valve opening
11. **Minimum valve opening  $P_{MIN}$** : minimum valve opening
12. **Deadband width  $db_2$** : deadband width of power gate

### 1.2.2 Turbine tab

The turbine tab allows to input:

1. **Time constant  $T_W$** : water inertia time constant
2. **Damping factor  $D_T$** : turbine damping factor
3. **Gain  $A_T$** : turbine gain
4. **No-load flow  $Q_{NL}$** : no-load flow at nominal head

## 2 Initial conditions

The initial output is equal to the generator mechanical power (base for power) at  $t = 0$  s.

## 3 References

- [1] "Review of Existing Hydroelectric Turbine-Governor Simulation Models", Argonne national Laboratory, August 2013